# Algebraic communication channels* 

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#### Abstract

Modern information theory studies various communication channels modelling certain situations. The basic matter of the present research is the information transmission process from a source to a receiver, and main parameters are the throughput/carrier capacity/transmission capacity and the information transmission speed.


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In the same time in any communication channel transformation of some words in others occurs, i.e. certain word function is realized. After focusing our attention exactly on this fact, a number of new situations arises. We consider them in the present paper.

Let $B=\left\{a_{1}, a_{2}, \ldots a_{m}\right\}$ is a finite alphabet and let $B^{*}$ is a set of all words of a finite length over the alphabet $B$. By a word function $T$ we mean a mapping $B^{*} \xrightarrow{T} B^{*}$, which we generally consider as identically defined.

## Instances:

1) if $B=\{0,1\}$ and $B^{n}=\{0,1\}^{n}$, then a word function of a form $B^{n} \rightarrow B$ is an ordinary/usual Boolean function depended on no more than $n$ variables;
2) The word function of a form $f(x, y)=x y$ is called a concanetation.

[^0]3) Consider a mapping $B^{n} \rightarrow B^{n}$ of the following form
$$
T_{y}(x)=x \oplus y,
$$
(1)
where $x, y \in B^{n}, y$ is a parameter, which defines a mapping $T$, and $\oplus$ is an operation of summation by mod 2 . The transformation collection $\left\{T_{y}(x)\right\}$ defines an additive communication channel. It is clear, that a transformation (1) is a special case of a general Affine transformation $B^{n}$ into itself given by means of a Boolean matrix $A$ and a vector и вектора $b$ :
$$
y=A_{x}+b
$$
(2)

In other words, we can think that a collection of matrices $\left\{A_{1}, A_{2}, \ldots . A_{m}\right\}$ is given, and every word $x$ at the entry can be transformed in one of the following words at the exit: $y_{1}=A_{1} x+b_{1}, \ldots y_{m}=A_{m} x+b_{m}$. Channels of a form (1) are a generalization of the well-known additive communication channel, see [3], [ 1 ].

In the general case it is convenient to think that there is a finite word set $M \subseteq B^{*}$ and a transformation group $T=\left\{T_{i}\right\}$ such that $T(M) \subseteq M$.

Thus, every transformation belonging to a family $T$ transfers a word from $M$ into a word from the same set.

Definition. A family of transformations $T^{*} \subseteq T$ defines an algebraic channel, if the following condition is satisfied $T_{i} \in T^{*} \rightarrow T_{i}^{-1} \in T^{*}$

This condition requires that any "transformed" word could be returned at the initial form by means of "the same" transformations. The following definition duplicates a standard definition of an error-correcting code.
Definition. A set $V \subseteq M$ we call a code correcting errors of a channel $T^{*}$, if a condition

$$
\begin{equation*}
T_{i}(u) \neq T(v) \tag{4}
\end{equation*}
$$

is satisfied for all $T_{i}, T_{j} \in T$ and for all words $u, v \in V$.

The condition (4) ensures an invertibility of every transformation from $T$ on "the restriction" на "сужении" $V \subseteq M$ and, by virtue of this fact, possibility to restore the initial message by its "image".

Definition. A neighbourhood of a 1 -st order of a word $v \in M$ we call a word set $S^{1}(v)$, generated by a family of transformations $T$, i.e.

$$
S^{1}(v) \stackrel{\operatorname{def}}{=}\left\{T_{i}(v), T_{i} \in T\right\}
$$

(5)

A neighbourhood of higher orders are defined inductively according to a formula

$$
S^{K}(v)=\left(S^{1}\left(S^{K-1}\right)(v)\right)
$$

In standard terms $S^{1}(v)$ is a column of the decoding table generated by word $v \in V$.

Every maximum efficiency code correcting errors of a channel Каждый код максимальной мощности, исправляющий ошибки канала $T^{*}$ we call an optimal code, and the efficiencies of the corresponding code we denote by мы назовем оптимальным, а мощности соответствующего кода обозначим через $A\left(M, T^{*}\right)$.

The following statement represents standard boundary of a density packing method and a Varshamov-Hilbert boundary in terms of first and second order neighbourhoods [ 1 ], [ 2 ]

$$
\text { Let } S^{1}(M)=\min _{v \in M}\left|S^{1}(v)\right|
$$

$$
S^{2}(M)=\max _{v \in M}\left|S^{2}(v)\right|
$$

Theorem 1. The following estimations are valid

$$
\begin{equation*}
\frac{M}{S^{2}(M)} \leq A\left(M, T^{*}\right) \leq \frac{M}{S^{1}(M)} \tag{8}
\end{equation*}
$$

A standard algorithm for construction of a code V , whose efficiency satisfies lower boundary from equation (8), consists in the following

1) As a point $v_{1}$ of a code $V$ we choose an arbitrary word from a set $M$ and construct a second order neighbourhood $S^{2}\left(v_{1}\right)$ of this word.
2) As a point $v_{2}$ we choose an arbitrary word $M_{1}=M / S^{2}\left(v_{1}\right)$.
3) As a point $v_{K}$ we choose an arbitrary word from $M_{K-1}=M / \bigcup_{i=1}^{K-1} S^{2}\left(v_{i}\right)$.
4) An algorithm finishes its work by a choice opportunity absence.

An efficiency of a code $V$ constructed by means of this algorithm depends on a next point choice strategy. However, there are special classes of channels $T^{*}$, for which described procedure always leads to the code with the same efficiency $A\left(M, T^{*}\right)$.

Theorem 2. If a family of transformations $T^{*}$ is a subgroup of a group T, then an optimal code efficiency is calculated by the following formula:

$$
A\left(M, T^{*}\right)=\frac{1}{\left|T^{*}\right|} \sum_{T i \in T} N(T i)
$$

(9)
where $N\left(T_{i}\right)$ is a number of fixed points of the transformation $\mathrm{T}_{\mathrm{i}}$, i.e

$$
N\left(T_{i}\right)=\left|v \in M: T_{i}(v)=v\right|
$$

(10)

The formula (9) is a classic Burnside schema (see [4]) applied to the described above situation.

Corollary 1 [1]. If $T^{*}=\left\{y_{1}, y_{2}, \ldots y_{m}\right\}$ is an additive channel generated by a group $G=\left\{y_{1}, y_{2}, \ldots . y_{m}\right\}$, i.e.

$$
\begin{equation*}
T_{i}(v)=v \oplus y \quad i=\overline{1, m} \tag{11}
\end{equation*}
$$

then the equity

$$
\begin{equation*}
A\left(B^{n}, G\right)=\frac{2^{n}}{m} \tag{12}
\end{equation*}
$$

is valid.

Corollary 2. If $T^{*}=\left\{T_{i}\right\}$ is a group of cyclical shift on $B^{*}$, i.e.

$$
T_{K}=\left(x_{1}, x_{2}, \ldots x_{n}\right)=\left(x_{n-\kappa}, x_{n-\kappa+1} \cdots\right)
$$

then we have

$$
A\left(B^{n}, T^{*}\right)=\frac{1}{n} \sum_{d / n} 2^{d} \varphi\left(\frac{n}{d}\right)
$$

and $\varphi(p)$ is the Euler function (function of a positive integer $p$ is defined to be the number of positive integers less than or equal to $p$ that are coprime to $p$ ).

## Literature.

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